Goals

* Add a back clamp to the back of Blam Bot
* ~~Work on GPS sensor~~
* Develop game strategies driver-controlled period
* Research teams ([RobotEvents.com API](https://www.robotevents.com/api/v2))

Today, Andrew, Clark, Cyrus, and Kaitlyn attended the meeting. Cyrus started building the back clamp of the robot. Andrew tested the GPS Sensor on the Moby Green Robot.